Reaction Wheel Disturbance Model Extraction Software, Phase II



Completed Technology Project (2007 - 2009)

Project Introduction

Reaction wheel mechanical noise is one of the largest sources of disturbance forcing on space-based observatories. Such noise arises from mass imbalance, bearing imperfections, and other sources. It takes the form of a number of discrete harmonics of the wheel speed, often also with a broadband noise component. Jitter problems can arise when harmonics sweep across observatory modes, and can be exacerbated by gyroscopically coupled spinrate-dependent wheel structural modes that dynamically amplify the tonal and broadband disturbances. For a well-balanced wheel, higher harmonic forces can be on the same order as the fundamental, therefore when there is a jitter problem it can occur at very low wheel speed. These higher harmonics are generally less well-characterized than the fundamental. The proposed Reaction Wheel Disturbance Model Extraction Software (RWDMES) is a tool for fitting a hybrid physical/empirical model to wheel induced-vibration data. The physical model captures the wheel structure including gyroscopic effects, while the empirical model captures the harmonic forcing and broadband noise. The Phase I effort demonstrated the ability to fit a highly accurate harmonic/broadband/structural model, including 43 harmonics up to 14.63 times the fundamental, to measured wheel disturbance data in a point-andclick environment in about 2 hours. The benefits of the technology include reduced program effort to produce wheel disturbance models, leading to more accurate jitter prediction earlier in a mission. This in turn allows jitter problems to be mitigated at the design stage when changes are relatively inexpensive.

Primary U.S. Work Locations and Key Partners





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Organizational Responsibility

Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

Lead Center / Facility:

Goddard Space Flight Center (GSFC)

Responsible Program:

Small Business Innovation Research/Small Business Tech Transfer



Small Business Innovation Research/Small Business Tech Transfer

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Organizations Performing Work	Role	Туре	Location
☆Goddard Space Flight Center(GSFC)	Lead Organization	NASA Center	Greenbelt, Maryland
Nightsky Systems, Inc.	Supporting Organization	Industry	Raleigh, North Carolina

Primary U.S. Work Locations		
Maryland	North Carolina	

Project Transitions

December 2007: Project Start

December 2009: Closed out

Project Management

Program Director:

Jason L Kessler

Program Manager:

Carlos Torrez

Technology Areas

Primary:

- TX04 Robotic Systems
 - ☐ TX04.2 Mobility
 - □ TX04.2.5 Robot
 Navigation and Path
 Planning

